

# **Consumer MEMS – A Technology Play** Frank Melzer, CEO Bosch Sensortec

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# 2011 key figures

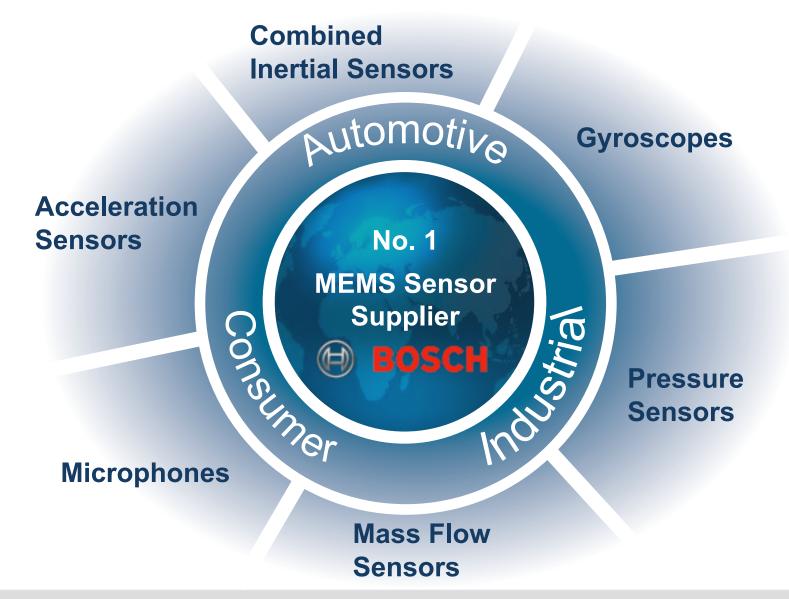
Bosch Group	<ul> <li>→ 51.4 billion euros in sales</li> <li>→ 303,200 associates including 38,750 in research and development</li> </ul>	
Automotive Technology	<ul> <li>→ 59% share of sales</li> <li>→ World's largest supplier of cutting-edge automotive technology</li> </ul>	
Industrial Technology	<ul> <li>→ 14% share of sales</li> <li>→ World's leading manufacturer of large gearboxes and of powertrain, packaging, and process technology</li> </ul>	
Consumer Goods and Building Technology <sup>1</sup> Including other segme	→ World's largest power tool manufacturer, leading the field in household appliances, heating and cooling, and security systems	

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# Bosch the global MEMS sensor leader

## Bosch: No. 1 global supplier of MEMS sensors

#### MEMS for **automotive** applications

#### **Automotive Electronics**



- Acceleration, angular rate, pressure, mass flow, torque and CO<sub>2</sub> sensors
- Headquartered in Reutlingen near Stuttgart, Germany

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MEMS for **consumer** applications

→

#### Akustica



- Acceleration ,magnetic, gyroscope and pressure sensors
- Headquartered in Reutlingen

- MEMS microphones
- Headquartered in Pittsburgh, PA, USA



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# A multitude of markets for MEMS





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6DoF

9DoF

DoF

0

# Smartphones & tablets – the technology drivers

- Geomagnetic sensors
- Acceleration sensors
- Gyroscopes
- Pressure sensors

#### The HW & SW Integration Challenge





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# **Today's Smartphone Sensors**

#### Gyroscopes

# Acceleration sensors

# Pres Co

- Very small LGA packages (3x3)
- Low power consumption
- Smallest IMU



- 2x2 LGA is the industry standard
- Lowest power consumption
- Use case optimized



eCompass

- A typical mid-end Smartphone solution
- 3-axis geomagnetic sensor + 3-axis accelerometer

# Pressure sensors



- Ultra low power
- High resolution
- Low TCO (stability)

#### Sensor data-fusion software provides the functional tie

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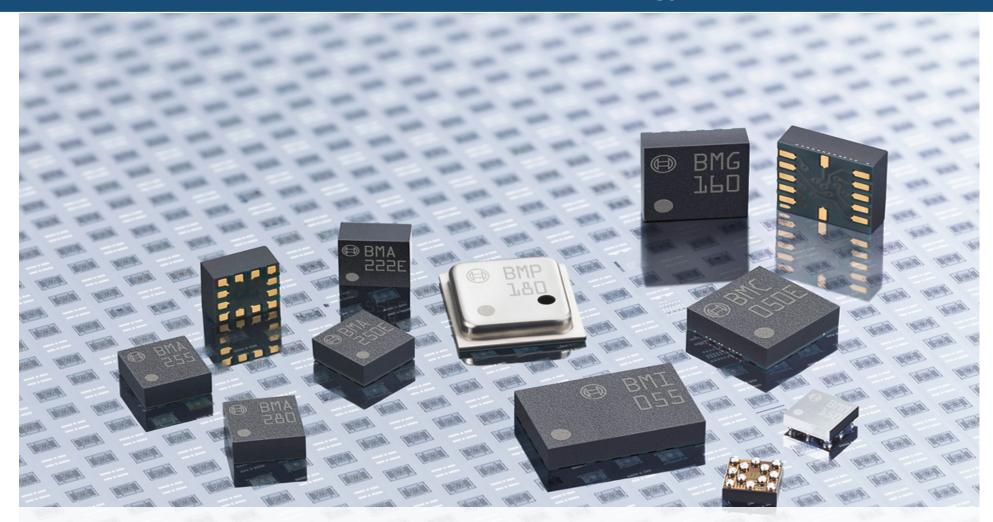
# Consumer MEMS driven by small packages

2005	2006	2007	2008	2010	2011	2012
o month	·	SHE CO	E	Brad Sec P		BUE CO
First triaxial acceleration sensor in 4x4 package	World´s smallest digital pressure sensor	World's first 3x3 digital acceleration sensor	Full portfolio of acceleration and pressure sensors	First 2x2 mm acceleration sensor	6DoF eCompass in 3x3	World's World's smallest smallest triaxial IMU gyroscope in 3x4.5 in 3x3 Announced today

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# **Key Success Factor - Technology**

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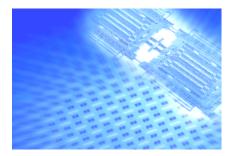


# Consumer MEMS – the solution challenge

#### Sensor Fusion Software

- 10 DoF solution available today (FusionLib)
- MEMS sensor in-house technologies required
  - Accelerometers
  - Magnetometers
  - Gyroscopes
  - Barometers
- → HW Integrating Components on the rise
  - 6DoF: eCompass & IMU
  - 9DoF: Accel+Gyro+Geomag









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Contradictory market requirements?

**1. Accelerometers market requirements:** 

full performance range (8 – 14 bits) & small 2x2 package

- 2. Gyroscopes market requirements: Low noise & low power modes
- 3. Geomagnetic Sensors:

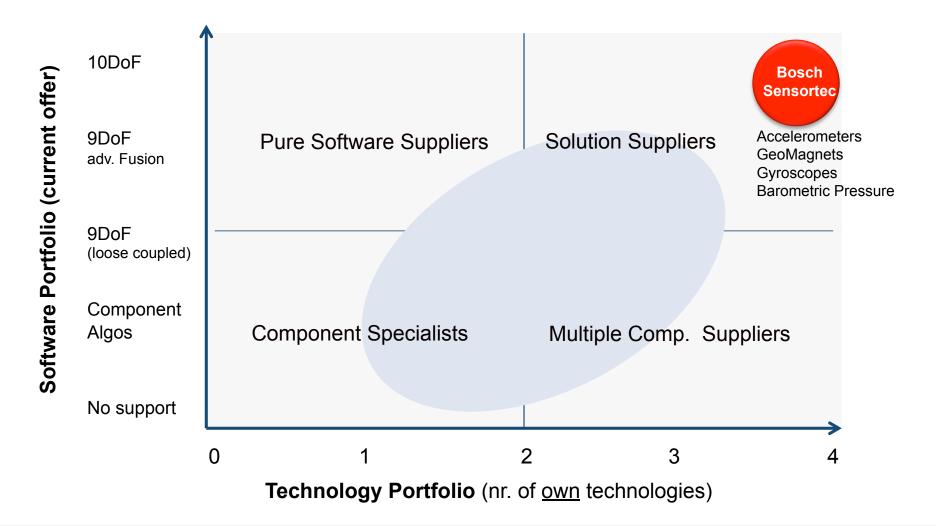
high range & high resolution Right combination of technologies is the key

4. Barometric Pressure sensors: high resolution & high accuracy





# **MEMS** Supplier positioning

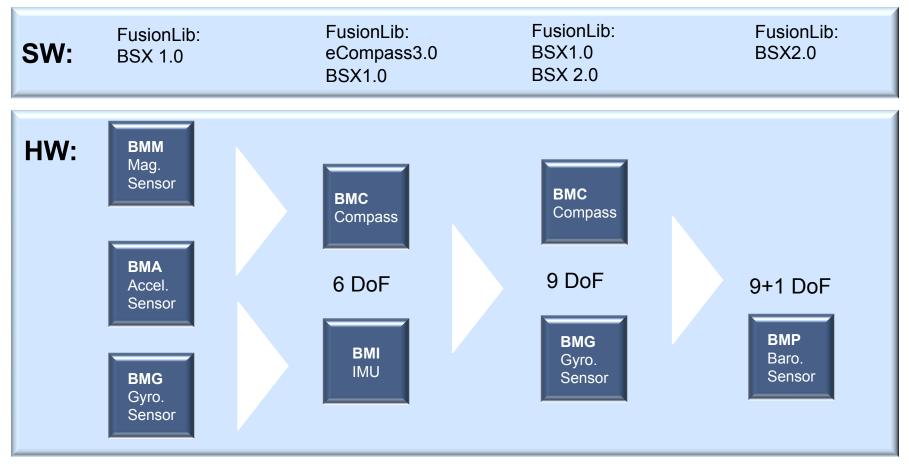


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## Hardware Integration paths



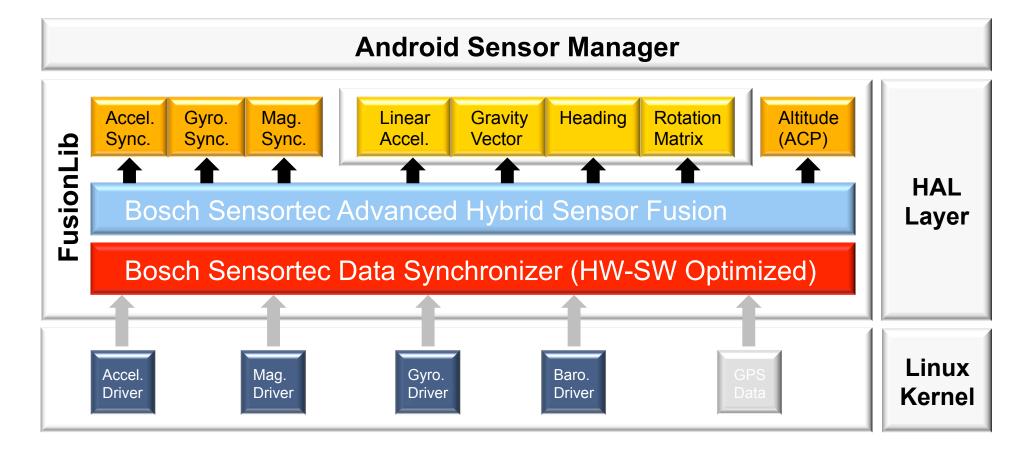
#### SW needs to be compatible to all HW combinations.

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# State of the art 10DoF Solution – Android example



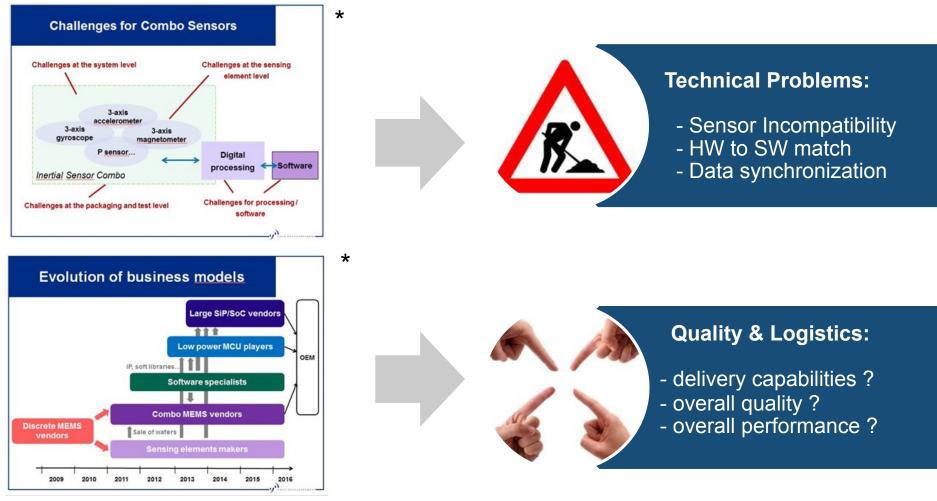
#### Customers requirements go well beyond standard HAL definition

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# 9DoF Sensor Data Fusion Challenges



\* As seen by Yole Développement

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# Sensor Fusion Challenge - Some Facts

- Matching Sensor Data: not all sensors work together
  - Sensor Performance matching is key
  - Sensor data timing matching is crucial but HW specific
- Geomagnetic sensor integration is the most complex task
  - Component integration requires Tools & Experience
  - SW integration requires specific Know-How
- Gyroscope and Barometric senor implementation is uncritical
  - As long as out of one hand solution (Ex. FusionLib)

#### Best sensor fusion approach by "out of one hand technologies"

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# How to get sensor fusion right

#### → Use the right SW approach

- Power & performance optimized (is usually HW specific)
- Compiled and proven libraries

#### Jse matched (right) components

- Allow no HW Incompatibility Interface but also timing problems
- Watch for matched performance performance grades

#### Shoose a supplier with all sensor technology know-how

- Geomagnetic sensor capability is key
- Do not accept patchwork solutions



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# Accelerometer Requirements for 10DoF

- Accelerometers: High Resolution & High Accuracy requirement
  - Requirement for single range operation mode: allows various apps running in parallel while no range switching is required (and possible)
  - Stable accelerometer operation also during temperature changes (TCO's are a significant performance deterioration)
  - Accelerometers contribute to all fused sensors output (Quaternion, heading & linear acceleration)

#### Accelerometer performance is key for overall performance



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# Magnetometer Requirements for 10DoF

- → Magnetometers: Balanced Power / Resolution factor @ high Range
  - Getting high effective measurement ranges & good power per resolution factors – is the industry dilemma – not for BMC's
  - SW algorithms provide ~ 50% of perceived performance. Due to the strongly HW dependency HW manufacturers need to supply SW.
  - Patchwork Combos: (eCompass & 9DoF from different suppliers) are "compromise solutions".

Magnetometers are a key component for 9DoF systems



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# Gyroscope Requirements for 10DoF

- → Gyroscope: low noise and low power requirement
  - Gyroscope is the most power consuming sensor thus power management is key. Fast turn-on and turn-off times are a conventional but effective way for reducing overall power dissipation (fast power up modes are required)
  - Gyroscope technology is the most complex technology (compared to magnetometers and accelerometers)
  - But Gyroscope system integration is an easy task...

#### Gyroscope size is a limiting factor for 9DoF package integration size



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# Technology enablers (some figures)

#### Robust and cost effective structures

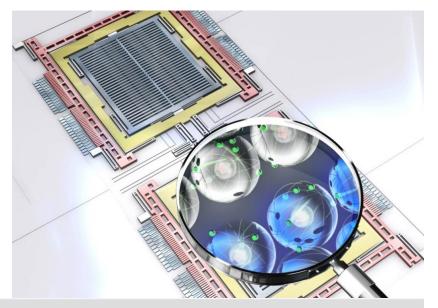
- Based on technology and implementation experience
- Shrinking is a major challenge for MEMS structures
- Driving at the (controlled) technical limit
  - amplitude change in micromechanical structure

#### ~4 fm

(compares to ~0.00001 x Si-Si distance or ~ radius of atomic nucleus)

capacitance change ~2 zF

 $(\mu - n - p - f - a - z)$ 10<sup>-6</sup> 10<sup>-21</sup> (compares to charge variation of ~0.06 electrons (at 5V))





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# Barometer Requirements for 10DoF

- → Barometric pressure sensor (barometer):
  - Resolution is key it defines the ability to distinguish very small altitude changes. This measurement can not be corrected or backed by another sensor signal
  - TCO (temperature coefficient): a low TCO guarantees the stability of the altitude measurement.

#### High performance barometers are the enablers for indoor navigation



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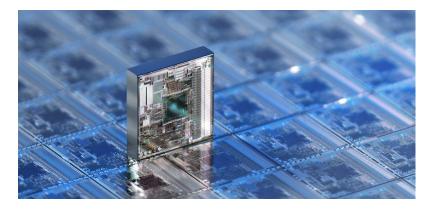
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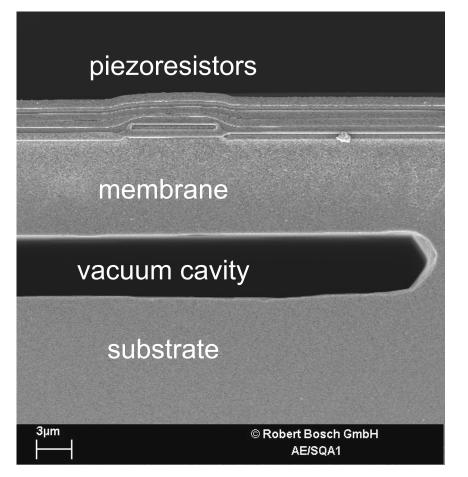
# MEMS technology – surface micromachining

APSM technology (Advanced porous silicon membrane)

Performance enabler:

A specific technology







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# MEMS Sensor fab in Reutlingen (biggest globally)

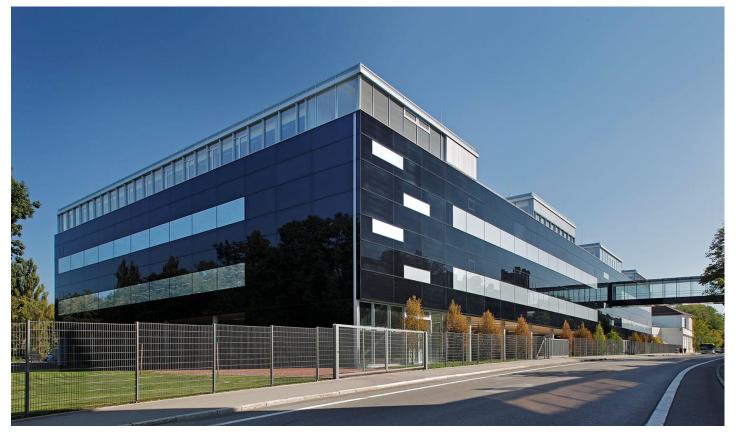
Employees	2 758				
Production area	34 300 sqm				
Minifactories	Wafer fab, sensor fron test center				
Products	IC, power S/C (chip ar (packaged, customer s				
150 mm module		200 mm module			
4 100 sqm 1 500 wafers/day Technologies: BCD1, 2, 3, 3s, 4, 4s CMOS, Bipolar, PSC bipolar, MOS Pressure sensors Inertial sensors Process: ≥ 0.5 μm		4 600 sqm 800 wafers/day Technologies: BCD4, 4s, 6, 6sCu Advanced CMOS, HVCMOS Pressure sensors Inertial sensors Process ≥ 0.18 μm			



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# Test Center in Reutlingen







#### **Highest installed MEMS test capacity globally**

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# Thank you!



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